

**Definition 0.0.1** (conditional expectation w.r.t. a partition). For any partition  $\mathcal{D} = \{D_1, \dots, D_n\}$  of  $\Omega$ , the conditional expectation of a simple random variable  $X$  is given by

$$\mathbb{E}(X|\mathcal{D}) = \sum_{i=1}^n \mathbb{E}(X|D_i)\mathbf{1}_{D_i} = \underbrace{\sum_{i=1}^n \sum_{j=1}^m x_j \mathbb{P}(D_j^X | D_i)}_{\text{a simple } \sigma(\mathcal{D})\text{-measurable r.v.}} \mathbf{1}_{D_i},$$

where  $\mathbb{E}(X|D_i) = \mathbb{E}(X\mathbf{1}_{D_i})\mathbb{P}(D_i)^{-1}$  is the usual conditional expectation, and  $\mathcal{D}(X)$  partitions  $\Omega$  w.r.t.  $X$ .

If we have two simple random variables  $X$  and  $Y$ , then

$$\mathbb{E}(X|Y) := \mathbb{E}[X|\mathcal{D}(Y)] = g(Y)$$

for some measurable function  $g$ , which, clearly, is  $\sigma(Y)$ -measurable.